# **USER'S MANUAL**

# MODEL: 3473-MRD & 3474-MRD

# **MOTORIZED ROTATING DRIVE**

PROPRIETARY

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**DRIVER CD** 

[located in pouch inside back cover]

#### SPECIFICATIONS Table 1. Model 3473-MRD Specifications

Rotation angle [from zero point]	+/- 200 deg max
Rotation repeatability	+/- 0.1 deg max
Rotation accuracy	+/- 0.2 deg max
Mechanical stops	+/- 200 deg max
Limit switches	+/- 195 deg max
Homing switch	0.0 deg
Drive system Gear type Mechanical reduction	Worm/Worm Gear 100:1
Stepper motor Motor type Motor part no Motor torque Motor frame size	Zeta 83-135 ES33B-DFR10 2.7N.m (382 oz.in) 34
Stepper motor controller	Compumotor Zeta 6104
Rotation axis scaling	approx. 6944 steps/deg
Software	

Motion architect [Supplied by Parker Hannifin] LabVIEW driver [ Supplied by GMW Associates]

#### SPECIFICATIONS Table 1. Model 3474-MRD Specifications

Rotation angle [from zero point]	+/- 200 deg max
Rotation repeatability	+/- 0.2 deg max
Rotation accuracy	+/- 0.3 deg max
Mechanical stops	+/- 200 deg max
Limit switches	+/- 195 deg max
Homing switch	0.0 deg
Drive system	
Gear type Mechanical reduction	Worm/Worm gear 100:1
Stepper motor controller	Compumotor Zeta 6104
Stepper motor	
Motor type	Zeta 83-135
Motor part no	ES33B-DFR10
Motor torque	2.7N.m (382 oz.in)
Motor frame size	34
Stepper motor controller	Compumotor Zeta 6104
Rotation axis scaling	approx. 6944 steps/deg

Software Motion architect [Supplied by Parker Hannifin] LabVIEW driver [ Supplied by GMW Associates]

#### WARNINGS [Refer to this section before operating motorized rotating drive]

Motorized rotating drive and electromagnet are under computer control. They may rotate at any time, personnel must remain clear.

Do not operate motorized rotating drive with the rolling base skirt panels removed.

Do not operate rolling/rotating base until it is secured in its final location.

It is recommended the rolling/rotating base is secured to an adequate concrete floor to prevent movement and possible injury to personnel during an earthquake.

Arrange cables and hoses so that they do not foul the worm/worm gear on the motor drive mechanism.

#### Introduction

The procedure to install the Motorized Rotating Drive Option onto an existing rolling/rotating base, is similar for either the 3473/3472/5403 or 3474 systems. Only one system installation is described in this manual. Refer to drawing no 11900800 for the 3473/3472/5403 system, and drawing no 11900801 for the 3474 system.

#### Installation of Spool Assembly and alignment to Rolling/Rotating Base

1. Firstly remove all the skirt panels from the rolling base.

2. Remove the M12 SHCS at locations 1 to 4 on the transition plate.

3. Install two M16 lifting eyebolts into two diagonal opposite corners of the transition plate.

4. Place spool assembly dwg no: 11900820 on top of assembly table, with the worm gear closest to table surface. Take care not to damage the worm gear.

5. Fit item 4 on drawing 11900801 Spool Spacer on top of spool assembly [3474 system only].

6. Using suitable lifting equipment raise the transition plate, and place on top of spool/spool spacer assembly. Check transition plate is correct side up. Counter bored holes should be on the top side.

7. Ensure the zero button on the spool assembly faces the front of the transition plate.

8. Secure the spool assembly to the transition plate with three M10 SHCS and lock washers at locations marked A, C, and E, on dwg no: 11900800/11900801. Tighten finger tight only.

9. Install spool alignment bush onto M10 SHCS and washer as shown on Drawing no: 11902640. Note wide end of alignment bush and washer fit under M10 SHCS head.

10. Fit alignment bush and M10 SHCS into the remaining spool assembly securing locations. They are marked B, D, and F, on dwg no: 11900800/11900801. Tighten finger tighten only.

11. Undo the rotation locks and rotate the rotating ring of the rotating base so that it is set to 0 deg. Then lock in place with the rotation locks.

12. Using suitable lifting equipment raise the transition plate and spool assembly, and move above the rolling/rotating base.

13. Rotate the transition plate and spool assembly so that the zero button is aligned with the rotating base top ring 0 deg position.

# MOTORIZED ROTATING DRIVE INSTALLATION Hardware

#### [Refer to this section only if MRD is not installed by GMW]

Installation of Spool Assembly and alignment to Rolling/Rotating Base [continued] 14. Slowly lower the transition plate spool assembly into the hole through the rotation base and rolling base assemblies. Take care not to damage the bronze worm gear at the bottom of the spool assembly.

15. Recheck the zero button is aligned with the 0 deg on the rotating ring of the rotating base.

16. Secure the spool /transition plate assembly with two M12 SHCS and M12 lock washers at locations marked 1, and 3. on dwg no: 11900800/11900801.Tighten finger tight only.

17. Install transition plate alignment bush onto M12 SHCS and washer as shown on Drawing no: 11902640. Note wide end of alignment bush and washer fit under M12 SHCS head

18. Fit transition plate alignment bush and M12 SHCS into the holes marked at locations 2 and 4 on dwg no: 11900800/11900801. Tighten finger tight only.

19. Next step is to align the spool assembly to the transition plate. Tighten the three M10 SHCS and spool alignment bushes at locations marked B, D, and F.

20. Fully tighten the three M10 SHCS at locations marked A, C, and E.

21. Remove the M10 SHCS and the spool alignment bushes at locations marked B, D, and F.

22. Install correct length M10 screws and lock washers, at locations B, D, and F and fully tighten.

23. Tighten the two M12 SHCS and transition plate alignment bushes at locations marked 2 and 4. Then tighten the two remaining M12 SHCS at locations 1 and 3.

24. Attach a dial indicator with a magnetic clamp to the underside of the rolling base top plate. Position the dial indicator probe so that it contacts the spool outer surface.

25. Undo the rotational locks. Rotate the rotating base from 0 through 360 deg and check the runout with the dial indicator. Maximum runout should be within: +/-0.2mm.

26.Remove the two M12 SHCS and alignment bushes at locations 2 and 4, and reinstall original M12 SHCS and lock washers.

27. If no further alignment is required then fully tighten the M12 SHCS at locations 1 thru 4.

28. If further alignment is required loosen the four M12 SHCS at locations 1 thru 4 and set so that they are finger tight.

29. Tap edge of transition plate to move as required to achieve runout specifications above. When runout specifications are met, fully tighten the M12 SHCS at locations 1 thru 4

#### Installation of Motor Drive Assembly to Rolling/Rotating Base (see drawing no 11900800/1)

1. Firstly install the ball plungers into the motor drive assembly guides. Note only the ball part of the plunger should protrude into the inside surface of the guide.

2. Fit the motor drive assembly guides to the underneath side of the rolling base using M8 SHCS and M8 ribbed lock washer. Note the locking detents must face to the front edge of the rolling base. Leave the M8 SHCS screws finger tight.

3. Place the disengage lever in the released position on the motor drive assembly.

4. Undo the rotational locks on the rotating base and rotate to the 0 deg position.

5. Slide the motor drive assembly into the motor drive guides . (Located on the front underneath surface of the rolling base

6. Squeeze the two release pins together and slide the motor drive assembly forward slowly until the lock bars just enter the motor drive assembly guides.

7. Move the motor drive assembly slowly inward with the release pins unrestrained until the motor drive assembly locks into the motor drive assembly guides detents.

8. Move the disengage lever to the engaged position while rocking the rotating base backwards and forwards slightly. The worm on the motor drive assembly will engage the worm gear on the spool assembly.

9. Fit G clamps to the outside surface of both the motor drive assembly guides. Adjust pressure to remove excessive play between the guides and the motor drive assembly. Tighten the M8 SHCS mounting screws. Move the disengage lever to the engage and disengage positions it should move freely. Readjust as required.

10. Measure the difference between the worm drive shaft centerline and the worm gear tooth centerline on the spool assembly. Record the difference, it will be within the range of 0 to 3mm.

11. Remove the motor drive assembly by squeezing the two release pins together and then sliding the motor drive assembly out of the motor drive assembly guides.

12. Refer to drawing no: 11900810/1. The worm and worm gear must be aligned on the same centerline to ensure correct gear meshing. Undo the four M6 SHCS and remove the worm drive and timing belt. Remove or add shim washers in four equal stacks to obtain the correct height required for the worm assembly. Reassemble the worm drive assembly using the four M6 SHCS and ribbed lockwashers, but leave finger tight. Do not refit the timing belt at this stage.

**Installation of Motor Drive Assembly to Rolling/Rotating Base** (see drawing no 11900800/1) 13. Reinstall the motor drive assembly refer to steps 5, 6, 7, and 8 above.

14. Slide the worm mount on the motor drive assembly forward until it is fully meshed into the teeth of the worm gear on the spool assembly. Tighten the four M6 worm assembly mounting screws.

15. Rotate the rotating base back and forth by slight hand force. If correct there should be no backlash in the system. If excessive backlash is found readjust as described above.

16. Remove the motor drive assembly by squeezing the two release pins together and then sliding the motor drive assembly out of the motor drive assembly guides.

17. Mark the position of the worm drive assembly relative to the stop block assembly.

18. Loosen the four M6 mounting screws and move the worm drive assembly backwards 0.1 to 0.2mm. This is the system backlash.

19 Retighten the four M6 mounting screws on the worm drive assembly.

20. Loosen the two M6 SHCS securing the stepper motor mounting bracket to the base plate.

21. Move the stepper motor towards the worm mount assembly.

22. Fit the timing belt.

23. Slide the motor away from the worm mount assembly until the belt is tight.

24. While holding the motor away from the worm mount assembly, tighten the motor mounting bracket M6 securing screws.

25. To check belt tension apply slight finger force in the middle of the belt. It should deflect approximately 3mm. Readjust if required as described above.

26. Reinstall motor drive assembly as described above.

27. Install the cable support with the M8 SHCS, flat and lockwasher as shown on dwg no: 11900800 and dwg no: 11900801.

28. Rotate the motor drive assembly cable around the cable support so that the cable enters the inside of the cable support. The cable should be free to slide within the cable support.

29. Recheck the motor drive assembly guide securing screws are tight.

30. Apply grease to the worm/worm gear as detailed on dwg no: 11900800/1

31. Refit both side skirt panels to the rolling base.

32. Located on the rear shirt panel is a rubber blank grommet. Remove grommet and cut center out and split along the radius.

33. Open grommet along radial split. Thread motor drive cable into grommet.

34. Push grommet into rear skirt panel cutout located in the middle of the skirt panel.

35. Refit rear skirt panel to rolling base. Take care not to trap the cable between the rolling base and the skirt panel.

36. Fit the disengage/engage label to the front skirt panel.

37. Fit the front skirt panel to the rolling base.

38. Fit the two caution labels to the rolling base top plate surface as shown.

#### **Running In Motorized Rotating Drive system.**

1. Remove Stop Block assembly from inside spool assembly. Undo four SHCS and lockwashers on the stop block assembly and remove. Refer dwg no: 11900820.

2. Run the MRD system at fast velocity setting i.e 2 to 5 for approximately one hour to bed in the worm and worm gear.

3. Finally reinstall the stop block assembly.

The motorized rotating drive option is now fully installed, refer to the following sections for operating instructions.

#### MOTORIZED ROTATING DRIVE INSTALLATION Hardware

#### Motor Drive Assembly Removal (see drawing no 11900800/1)

1. Remove front and rear skirt panels on rolling base.

2. Place the disengage lever in the released position.

3. Squeeze the two release pins together and slide the motor drive assembly outward until the motor drive assembly clears the mounting guides..

4. Rotate the motor drive assembly cable around the cable support so that the cable releases from the cable support.

#### Motor Drive Assembly Fitting (see drawing no 11900800/1)

1. Slide the motor drive assembly into the motor drive guides .

2. Squeeze the two release pins together and slide the motor drive assembly forward slowly until the lock bars just enter the motor drive assembly guides.

3. Move the motor drive assembly slowly inward with the release pins unrestrained until the motor drive assembly locks into the motor drive assembly guides detents.

4. Rotate the motor drive assembly cable around the cable support so that the cable enters the inside of the cable support. The cable should be free to slide within the cable support.

5. Fit motor drive assembly cable into grommet on rear skirt panel.

6. Replace back skirt panel on rolling base.

7. Replace front skirt on rolling base.

8. Move the disengage lever to the engaged position while rotating the electromagnet slightly and slowly back and forth. The lever will lock in the engaged position.

**Rolling/Rotating Base Installation** (refer to electromagnet user's manual for more details). 1. First fit electromagnet to rolling/rotating base, and move to desired location.

2. If magnet cable and hoses enter rotating base from floor it is recommended to fit floor spacers to provide additional clearance for the hoses and cables. See drawing no: 11902620 and 11902621. Level the base as detailed below.

3. If cables and hoses enter from above magnet/rolling/rotating base then the floor spacers are not needed. It is important that the base is leveled in its final location. Screw down the four support legs located on each corner of the rolling or rolling/rotating base until the wheels clear the floor by 6mm (.25"). Check the base is level in both directions. Then secure the support legs with the locknut.

4. Secure rolling/rotating base to an adequate concrete floor to prevent movement and possible injury to personnel during an earthquake.

#### MOTORIZED ROTATING DRIVE INSTALLATION Hardware

#### Stepper Motor Controller Installation (see drawing no 11901020)

1. Connect the motor drive assembly cable to the stepper motor controller. Cable has two plugs, one connects the motor power and the other connects the limit and homing wiring to the controller.

2. Connect the serial communications cable into Com 1 on the stepper motor controller.

3. Connect the other end of the serial communications cable into the control computer's serial port.

4. Check the Controller input power requirement, normally 115V. Connect the AC power cord to the stepper motor controller and the other end to the correct voltage outlet.

#### MOTORIZED ROTATING DRIVE SETUP Software

#### **Software Requirements**

- PC with Intel Pentium/Celeron family, or AMD K6/Athlon/Duron family, or compatible processor, 300 megahertz or higher processor clock speed recommended
- 512Mb RAM memory required, 1Gb RAM memory or more recommended.
- CD-ROM drive or DVD drive for software installation.
- USB 2.0 port for using USB-RS232 converter. If native Serial port present, USB port is not required for Motorized Rotating Drive Software.
- SVGA monitor running 1024 x 768 pixels. [Note1]
- Windows XP Operating System software.
- LabVIEW for Windows V8.2 or later. <sup>[Note 2]</sup>
   Motorized Rotating Drive software can also be supplied as an executable file and run directly from the Windows Operating System. In this case LabVIEW for Windows V8.2 is not required.

#### **Software Installation**

The Motorized Rotating Drive LabVIEW driver and support files are all located in a directory called MRDrive.

To install the driver follow the directions given below.

- 1. Insert CD of the Motorized Rotating Drive software into CD-ROM Drive.
- Open the Windows Explorer to access the software in CD. The software on the CD is located at directory CD drive:\MRDRIVE\LabVIEW 8.2 MRD.prg Setup file for Zeta stepper motor controller. MRD V2.0a.llb MRD driver library file. [All sub VI's are inside the llb file] The top level vi is: MRD Driver.V2.0a.vi
- 3. Copy the files on CD to computer hard drive in a proper directory. Note: MRD.prg and MRD V2.0a.llb must be in same directory.

**Before** running the Motorized Rotating Drive software set the Com Port control to match the Com Port being used on the control computer.

#### Note:

- 1. Using screen resolutions other than 1024 x 768 means all items on the LabVIEW front panels will have to be resized by the end user.
- 2. The executable program file cannot be altered by the end user. Consult GMW if the Motorized Rotation Drive software is required as an executable file.

#### MOTORIZED ROTATING DRIVE OPERATION

#### To Start the Motorized Rotating Drive Software

Click the LabVIEW **Run** button or use CTRL+R on the keyboard.

When the software starts running, message "Sending Setup File to Zeta Controller \*Please Wait\*" appears. It should stay on for several seconds. Do not operate the software at this stage. After several seconds another message should appear: "System Running. The system is then ready for accepting commands.

#### To Stop the Motorized Rotating Drive Software

Click the blue **STOP PROGRAM** button located at the lower RH corner of the screen. Use this button to stop the software at all times if possible. Any other way of terminating the software will possibly cause serial port communications problems. To restore communications sometimes requires rebooting the host computer.

#### **Motorized Rotating Drive Software Default Settings**

The Magnet Control System software will open with all parameters set to the default settings. To change the default of a control follow the instructions listed below.

- 1. First stop the software by clicking on the STOP PROGRAM button.
- 2. Then set the control to the desired default value.
- 3. Right mouse click on the control and select Data Operation.
- 4. Click on the selection Make Current Value Default. Save the new setting.
- 5. Restart the Motorized Rotating Drive Software by clicking on the LabVIEW run arrow at the top left screen.

#### **Motorized Rotating Drive Software Help**

On screen help is available. To use the on line help use a  $\mathbf{CTRL} + \mathbf{H}$  from the keyboard to open the help window, and then move the cursor over the control or indicator on the front panel. A description of the control or indicator function will appear in the help window.

SETUP PANEL	
MRD Port:	Click on the Drop-Down arrow button. Selects the computer serial port used to communicate with the stepper motor controller.
Motor Controls:	Sets the velocity value, acceleration value of the stepper motor.
Home Motion Controls:	Sets the acceleration, deceleration and velocity of the stepper motor when homing to the 0.0 deg position.
AUTO START ON/OFF:	When AUTO START is set to <b>ON</b> the Set Position [deg] is controlled by the Up an Down arrows on the computer keyboard. A position value can also be directly entered from the numeral keypad. By default the lowest significant digit is controlled and rolls over to the next highest digit. Roll over occurs between the lowest to the most significant digit. Press the ENTER key to start rotation to the set position.
GO TO SET POSITION:	Click on the GO TO SET POSITION button will start the motion to the position defined by Set Position [deg] control.

#### MOTORIZED ROTATING DRIVE OPERATION

[Continued]

#### MAGNET ROTATION CONTROLS

Home CW Control:	Makes the motorized rotating Drive rotate in a clockwise direction			
	until it finds the home position at 0.0 deg and resets the current			
	position counter to 0.0 deg. [See initial setup information below]			
Home CCW Control:	Makes the motorized rotating Drive rotate in a counterclockwise			
	direction until it finds the home position at 0.0 deg and resets the			
	current position counter to 0.0 deg. [See initial setup information below]			
Counter Reset Control:	Resets the current position counter to 0.0 deg.			
Velocity Value Control:	Sets the velocity of the stepper motor.			
<b>Acceleration Value Control</b>	Sets the acceleration of the stepper motor.			
	Note: Velocity and Acceleration value settings only change while			
	motor is in motion. The values for both velocity and acceleration are			
	relative values, not absolute value.			
Start Motion CCW Control	: Starts the motorized rotating drive rotating in a counterclockwise			
	direction until limit switch is reached, or the Stop Motion button in			
	pushed.			
<b>Start Motion CW Control:</b>	Starts the motorized rotating drive rotating in a clockwise direction			
	until limit switch is reached, or the <b>Stop Motion</b> button in pushed.			
Stop Motion Control:	Stops the motorized rotating drive rotating at any time.			
<b>Emergency Stop Control:</b>	Stops the motorized rotating drive rotating INSTANTLY.			
	Since this action puts high stain on all mechanical components, only			
	use in an emergency.			
Stop Program Control:	Stops the motorized rotation drive software running.			

#### MAGNET ROTATION STATUS

Actual Position Indicator: Shows the motorized rotation drive current position on a digital display. Units are in degrees from the initialized zero position.

#### **System Initial Setup**

Press either the Home CW or Home CCW button. The base will rotate to approximately the 0 deg position and stop. Set the Velocity to 0.1 and move the base to exactly the 0 deg position using either the CW or CCW buttons. Once the base is aligned on the 0 deg position, press the Counter Reset button. The system is ready to be used. Note if the stepper motor controller is reset then this process must be repeated.

#### **Hardware Limits**

The hardware CCW and CW limit switches operate at approximately -195 deg and +195 deg respectively. After the limit switch has operated the rotation of the motorized rotating drive will decelerate at the same rate as set by the software acceleration control setting and then stop. A 5 deg overrun has been allowed for before the mechanical stops operate.

#### **Mechanical Stops**

The mechanical stops operate at -200 deg and +200 deg stopping any rotation beyond these positions.

#### TROUBLESHOOTING/ TECHNICAL SUPPORT

#### Troubleshooting

Symptom 1: Clicking sound coming from stepper motor while base is rotating [motor stalling].

Cause of Problem:

- [a] Worm/Worm Gear not lubricated.
- [b] Timing belt not set to correct tension, causing belt to slip during operation.
- [c] Spool assembly not running concentrically with rotating base.
- [d] Worm/Worm Gear not aligned with each others centerline.
- [e] Worm/Worm Gear meshed too tight together.
- [f] Pulley slipping on either stepper motor, or worm assembly shaft.
- [g] Rolling/Rotating base is not level.
- [h] Too much friction in the rotating base.
- [i] Cables or hoses stopping free rotation of rotating base.
- [j] Running stepper motor at too higher speed. Recommend velocity setting of 0.5 for 3474 MRD, and 1.0 for 3473 MRD.

Remedy: Diagnose fault, and refer to the appropriate section of this manual for corrective action.

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Symptom 2: Rotating Base does not rotate to correct position.

Cause of Problem: [a] Controller has lost rotational reference point.

Remedy: Follow instructions for System Initial Setup.

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<u>Symptom 3</u>: No rotation from rotating base.

Cause of Problem:

[a] No AC power to Zeta controller.

[b] Serial communications cable not connected to host computer.

[c] Motor and limit switch cable not connected to Zeta controller.

Remedy: Check system wiring and AC power.

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#### TROUBLESHOOTING/ TECHNICAL SUPPORT

#### **Technical Support:**

Technical support is available by contacting GMW by Telephone, Fax or Email.

GMW Associates 955 Industrial Rd. San Carlos, CA 94070 USA

Tel: (650) 802-8292 Fax: (650) 802-8298

Email: sales@gmw.com.

User Comments: Please forward comments on this product to GMW at the above address

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## MOTORIZED ROTATING DRIVE SOFTWARE

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#### MOTORIZED ROTATING DRIVE SOFTWARE DOCUMENTATION

#### SOFTWARE REVISION LIST

The Software revision number has the following format.



- V1.0 First release.
- V1.1 Fix communications bug. Add speed ramp down on approaching soft limit.
- **V2.0** Rewrite MRD software driver using Labview Visa port drivers.

## DRAWINGS













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REVISIONS DESCRIPTION DESCRIPTION DESCRIPTION DEAFT DATE APPROVED 07/07/97 0.0/01CLAS 0.0/01C	8 03/07/08 C.DOUGLAS & PULLEY/BEARING VIEW, ADD NOTE 2 08/21/08 C.DOUGLAS		SHIM WASHER, 14 X 26 X 0.1MM THICK SETSCREW 8-32 x 1/4" UNC PIN, SPRING M4 X 18L, SP/S BEARING, THRUST 0.5" SHAFT, BERG BEARING, RETAINING RING, BERG BARING, NEEDLE ROLLER, SDP	SPACER, WORM WORM SHAFT -18 PULLEY, 18 TEETH [for 0.5" shaft] BERG WORM	WORM MOUNT         DESCRIPTION         NOTE           BER         PORM MOUNT         DESCRIPTION         NOTE           DD         NOT SCALE         DE         NOT           FROM DRAWING         GATA         DE         NOT           DD         NOT SCALE         GATA         NOT           FROM DRAWING         955 Industrial Rd, San Carlos, CA 94070         94070           NUMES INVESTIGATION         Tel: (650)802-8292. Fax: (650)802-8298.         NOT           XXX         #100         #001         DRIVE           XXX         #100         #001         DRIVE           XXX         #100         #001         MOT         DRIVE           XXX         #100         #001         MOT         DRIVE           XXX         #100         #001         MOT         DRIVE           XXX         #100         MOT         MOT         MOT           XXX         #100         MOT         MOUNT         MOT           XXX         #100         MOT         MOT         RV	Scale         1:1         WT kg         SHEET         0F         1
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	REVISIONS       REV     DESCRIPTION       D     DESCRIPTION       D     ADD     DRAFT     DATE       ADD     TOP     VIEW, HORZ/MTC     I12/06/92     A.MARTIN       C     ADD     TOP     VIEW, HORZ/MTC     I11/13/97     G.DOUGLAS       D     ADD     MOUNTING     HOLES, CHG     PARTS     LIST     11/13/97     G.DOUGLAS       E     CHG     POSITION OF TIEMS     7     & 8     NOW FITTED     11/13/97     G.DOUGLAS       F     ADD     DETAIL     @ 22, AND NOTE     2     MOUNTING     HOLES     C       ABAR     ABAR     ABAR     ABAR     ABAR     ABAR     ABAR     ABAR       E     CHG     POSITION OF TIEMS     7     & 8     NOW FITTED     11/13/97     G.DOUGLAS       MOUNTING     C     ADD DETAIL     A2, AND NOTE     2     MOUNTING     ABAR     ABAR       ABAR     ADD     DETAIL     A2, AND NOTE     2     MOUNTING     C     DOUGLAS       ABAR     ADD     DETAIL     A2, AND NOTE     2     MOUNTING     D     C       C     ADD     DETAIL     A2, AND NOTE     2     MOUNTING     D     D <td>FIT LABEL ON CENTER LINE 35mm UP FROM BOTTOM OF SKIRT         • APPLY GENERAL PURPOSE GREASE TO INTERNAL THREAD [x4]         22       1 10900210         21       1 10900210         21       1 10900200         21       1 10900200         21       1 10900200         21       1 10900200         21       1 10900200         22       1 605-677         RUBBER, CMW MGNET SYSTEMS         20       1 605-677         RUBBER, PLUG, 30MM DIA OD R-S         19       26         10       101         117       16         16       10         17       16         18       26         10       103         117       16         110       10         125       A         MASHER, FLAT M6, S/S         15       16         16       10         17       16         16       10         15       16         16       10         17       16         18       MASHER, LOCK M10, S/S         19       125         10       125<td>ID         ID         ID&lt;</td><td>2     117801791     SKIRT PANEL, FRONT SIDE       1     1     17801810     BASE PLATE       ITEM arr     PART IN 12/06/92     BASE PLATE     DESCRIPTION       MARTIN     17/06/92     FROM DRAWING     MOTE       A.MARTIN     17/06/92     PRON DRAWING     GTMW       A.MARTIN     17/06/92     PRON DRAWING     94070       A.MARTIN     17/06/92     FROM DRAWING     94070       CHECK     DATE     DATE     DATE       DAME     DATE     DATE     DATE       NAMERENIA     DATE     DATE     DATE       NOMERENIA     DATE     DATE     DATE       NOMERENIA     DATE     DATE     DATE       NOMERENIA     DATE     NOMERENIA     100002-8292. Fax: (650)802-8298.       ENGINEERIA     NAMERENIA     TERMERS     955 Industrial Rd, San Corlos, CA 94070       ENGINEERIA     DATE     NOMERENIA     TERMERS       A.MARTIN     TATE     ADATE     2474       XXX     ADATE     MODEL:     3474       A.MARTINSIG     TERMERS     ADATE     11801800       AUTOCAD     2000     DATE     PROMING NO.       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