USER'S MANUAL

MODEL: 3474-140 MODEL: 3474FG-140

250MM ELECTROMAGNET

Date Sold _____

Magnet SN _____

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Section 1 SPECIFICATIONS Table 1. Model 3474-140 General Specifications

Pole Diameter	250 mm (10 inch)
Pole Gap *	0 - 160 mm (0 to 6.3 inch)
Standard Pole Caps:	250 mm (10 inch) cylindrical
	200 mm (8 inch) tapered
	150 mm (6 inch) tapered
	100 mm (4 inch) tapered
	75 mm (3 inch) tapered
	50 mm (2 inch) tapered
	2 5 mm (1 inch) tapered
<u>^</u>	series connection
Coil Resistance (20° C)	0.44 ohm
Maximum Resistance (hot)**	0.54 ohm
Maximum Power [air]	40A/22V (0.88kW)
Maximum Power [water]	140A/76V (10.6kW)
Self Inductance	80mH (measured at 5Hz)
Water Cooling (18° C)	15 liters/m (4 US gpm) 2.0 bar (30 psid)
Overtemperature Interlock	Elmwood 3450G thermal sensor part number 3450G 611-1 L50C 89/16 mounted on each coil and wired in series. Contact rating 120Vac,0.5A. Closed below 50 ⁰ C.
Water Flow Interlock	Johnson Controls flow switch part number F61KD mounted on outlet side of water circuit. Contact rating 120Vac/16A, 240Vac/8A non-inductive Set to open at a flow of less than 10 liter/min (2.7US gpm)
Dimensions	Drawing 11801602/11801603 920mm W x 636 mm D x 864 mm H (36.2 inch W x 25.0 Inch D x 34.0 inch H)
Weight	1800 kg (3970 lb)

* The 3474FG-140 is a fixed pole gap magnet. Pole gap can be fixed in the range of 5 to 160mm

******CAUTION - The value of maximum coil resistance given should not be exceeded. At this resistance the coils are at maximum safe temperature for continuous operation.

Section 1 SPECIFICATIONS Table 2. Model 3474-140 Electrical and Water Connections

DC Current (Refer to Drawing 11801602/11801603) Right hand terminal Negative Left Hand terminal Positive

Ground

An M6 screw is provided alongside the dc current connections to enable the magnet frame to be grounded according to local safety regulations. It is normally appropriate to connect the magnet frame to the power supply ground.

Interlocks (Refer to Drawing 11801602/11801603)

- 1 Water flow
- 2 Water flow
- 3 Overtemperature
- 4 Overtemperature
- 5 No connection
- 6 No connection
- 7 No connection
- 8 Control ground

Normally open. Closed when flow over 10 l/min (2.7 USgpm) Normally closed. Open when coil temperature exceeds 50^oC.

Water (Refer to Drawing 11801602/11801603) outlet 3/8 inch NPT inlet 3/8 inch NTP (mating couplings for 1/2 inch hose provided)

CAUTION - Ensure that the high current connections are tight. Loose connections may lead to oxidation and overheating. The field stability may be degraded and the current terminations damaged.

WARNINGS

REFER TO WARNINGS BELOW BEFORE OPERATING ELECTROMAGNET

1 Personnel Safety

In operation, the magnet fringing field is in excess of 0.5mT (5G). This can cause malfunctioning of heart pacemakers and other medical implants. We recommend that the fringing field should be mapped and warning signs be placed outside the 0.5mT (5G) contour. Entry to this region should be restricted to qualified personnel

2 Ferromagnetic Objects

During operation the magnet exerts strong magnetic attraction towards ferromagnetic objects in the near vicinity of its pole gap or coils. Loose objects can be accelerated to sufficient velocity to cause severe personnel injury or damage to the coils or precision pole faces if struck. Keep ferromagnetic tools clear!

3 Arcing

This magnet stores considerable energy in its field during operation. Do not disconnect any current lead while under load or the magnetic field energy will be discharged across the interruption causing hazardous arcing.

4 Coil Hot Resistance

Do not exceed the maximum coil hot resistance given in the specifications or coil overheating and possible damage may occur.

5 Interlocks

These should *always* be connected if the magnet is operated unattended, to avoid the possibility of coil overheating caused by excessive power dissipation or inadequate cooling.

6 Watches, Credit Cards, and Magnetic Disks

Do not move magnetically sensitive items into the close vicinity of the magnet. Even some antimagnetic watches can be damaged when placed in close proximity to the pole gap during operation. Credit cards, and magnetic disks are affected by magnetic fields as low as 0.5mT (5G). Depending on the previous operating field and the pole gap, the remanent field in the gap can be in excess of 50G (5mT) with the magnet power supply off or disconnected.



Model 3474 System Installation; Minimum Facility Requirements for Systems with Field Reversal, High Precision Systems and High Power Systems installed in North America

Floor Space:

Magnet Floor Area: 830 x 830mm (33 x 33") Floor Capacity: 1800kg (3,980lb) Power Supply & Rack Floor Area: 700 x 900mm (28 x 36") Floor Capacity: 100kg (220lb) An area for access to the Magnet and Power Supply must be provided. The total area for the system and comfortable operation is about 3 x 3m (10 x 10ft). The area should be clean and free from obstructions.

Electrical Service:

	Systems with Field Reversal or	High Power System
	High Precision Systems.	
MPS Power:		
Power Supply:	Power10 P83C-100150	Power10 P86C-100200
	Danfysik 853-160A/80V	
Voltage:	208Vac, Three Phase,	208Vac, Three Phase,
	50 – 60Hz	50 – 60Hz
Current:	56 Amps per phase	74 Amps per phase
Circuit Breaker:	60 Amps minimum	80 Amps minimum
Power Cable:	4 Conductor, 4AWG Min.	4 Conductor, 3AWG Min.
Mains Outlet:	Nema 15-60R or equivalent	Hard-wired in to electrical panel
Mating Plug:	Nema 15-60P or equivalent	(no suitable plugs available)
Auxiliary Power for Rack:		
Voltage:	115Vac, Single Phase	
Current:	15A	

Note: Due to liability and insurance reasons, the mains power installation and connections must be completed by the facility electrician.

Water Cooling:

Water Temperature:	15°C to 20°C, non-condensing. Specifications given at 18°C
Flow Rate:	15 liters / minute (4 US gpm)
Pressure:	2 bar (30 PSID)
Water Hose:	12.5mm I.D. (1/2"), rubber, 2 x 5m long minimum
Plumbing Fittings:	To connect 12.5mm hose to water source and drain. (It is recommended to have a 50
	micron water filter to trap debris on the facility water source and shutoff valves on the
	water source and drain.)

System Computer (if required and not provided by GMW):

Processor:	Intel Pentium III, 500MHz PC or better
Memory:	128MB RAM
Free Drive Space:	500MB
Interface:	IEEE-488 (GIPB), National Instruments GPIB-PCII/IIA, P/N: 777158-01
Monitor Resolution:	1024 x 768 or better
Operating System:	Windows ME / 2000 / XP pro / NT4

Lifting Equipment for Installation:

Forktruck or other lifting device with minimum safe lifting capacity of 2000kg Nylon Slings with minimum safe lifting capacity of 2000kg

Continued...

GMW



General:

The Purchaser must provide all equipment and labor for delivering the equipment from the delivery dock to the installation site. You should have a User Manual for the Model 3474 250mm Electromagnet and for the magnet power supply. Please provide these to the person who will be responsible for the System installation. If you do not have the User Manual or need to discuss details of the installation please call GMW. If a GMW Engineer is to supervise the installation any delays caused by inadequate preparation may result in additional charges for Engineering Time.

Model 3474 System Installation; Check List

Site:

_____ Floor space and work space cleared and ready for equipment installation.

____ Appropriate electrical services installed

Materials Required:

____ Power Plugs

- ____ Power Cable
- _____ Facility Electrician ready to make mains connections to power supply at the time of system install

____ Cooling water supply installed with shut-off valves

Materials Required:

- ____ 12.5mm I.D. (1/2") water hose, 5m for source and 5m for drain
- ____ Water hose fittings appropriate for installed plumbing
- ____ Water hose clamps

Misc. Items (to be provided by facility):

Tools:

- ____ Power Drill with 5/16" socket (to open magnet crates)
- _____24mm combination wrench (open and box end)
- _____24 mm socket wrench (for attaching the angle brackets to the magnet)
- <u>34</u>" socket wrench (for removal of magnet from shipping crate)
- _____Nylon lifting slings, chains, cables and other rigging equipment suitable for lifting magnet.

Other Items:

4 " x 4" x 3" wood blocks. (about 4 – 6 pieces)

_____ 3' x 3' ¾" plywood

All required materials on this list are to be provided by the facility.

If you are providing your own equipment rack, it must be a minimum of 760mm (30") deep.

Note: The weight of an assembled 3474 magnet system is just over 4300 lbs. It is not possible to rig and move this magnet by hand, so use of proper lifting equipment is required (either an appropriately rated lift truck or a traveling crane). It is the responsibility of the facility to provide the means to move and lift the magnet for assembly on to its base and move it to its final installed position. If the means to do this is not available in-house, the customer may be required to hire an outside rigging company to lift and move the magnet. Scheduling of the riggers is the responsibility of the customer. Should the installation time be extended due to problems with the rigger scheduling, GMW reserves the right to bill for additional time beyond the original contracted amount.

Important: Due to liability and insurance reasons, the mains power installation and connections must be completed by the facility electrician. The GMW engineer will not complete the mains power connection. Please ensure that the facility electrician is available to do this work.

INSTALLATION

Caution: This is a heavy system. The magnet mass is approximately 1800 kg (4000 lb) so lifting equipment of this capacity should be used to shift the magnet. Two lifting eyes threaded M33 are provided and they can be used in several holes. Be sure to ensure the eyes are screwed fully home before use. Flexible lifting slings of at least 4000kg (9,000 lb) lifting capacity are recommended to avoid damage to the magnet. All movement, lifting and installation of the 3474 Electromagnet must be under the supervision of an experienced person to prevent the possibility of serious injury or damage to the Electromagnet and associated equipment.

Mounting Position

The magnet can be operated in any position. 45 degree mounting angles are available to allow the field axis to be horizontal with the yoke inclined back at 45° for access from the horizontal and vertical direction. Refer to drawing 11900930 for showing the 45° mounting arrangement.

Alternatively, vertical mounting brackets can be used to position the field axis vertically. In each case the magnet should be oriented with the water lines below the electrical connections to reduce the chance of water leakage shorting electrical connections. Refer to drawing 11900490.

Unpacking Instructions and Damage Inspection

To unpack the electromagnet please use the following procedure (Refer to Drawing 18800191).

- 1. First remove all of the "Hex Head Screws" located at the lower edge of all the side panels of the "Crate Top Cover".
- 2. Gently rock the "Crate Top Cover" to work it loose from the shipping crate base.
- 3. Use one person on each side of the shipping crate grip the side panels of the Crate Top Cover. Lift "Crate Top Cover" high enough to clear top of electromagnet, walk cover sideways to clear area and place on floor.
- 4. Inspect the magnet to ensure that no damage has occurred to the magnet in shipment. If damage is evident report the damage in detail to the shipper for claim and simultaneously notify GMW in case assessment of the damage must be made. If no damage is found proceed with magnet unpacking and installation.
- 5. Remove the M16 Hex Bolts that secure the magnet to the steel shipping angle brackets.
- 6. Remove the hex lag bolts that secure the steel "shipping angle brackets" to shipping crate base, and remove shipping angle brackets.
- 7. Install M16 lifting eye and washer to top of magnet yoke, screw down firmly.
- 8. The magnet is now prepared for final installation, follow the appropriate following procedure to install to 45°, vertical or direct mounting.

Direct Mounting

- 1. With suitable lifting equipment (e.g. 4000kg (9000 lb.) minimum safe lifting rating), lift magnet 50mm (2") clear of shipping crate base.
- 2. Slide shipping crate base clear.
- 3. Lower magnet to 50mm (2") above floor.
- 4. Move magnet to final location and secure using the steel shipping angle brackets. The brackets can be modified to suit installation space needs.

INSTALLATION

45° Mounting (Refer to Drawing 11900480)

- 1. With suitable lifting equipment (e.g. 4000kg (9000 lb.) minimum safe lifting rating), lift magnet 50mm (2") clear of shipping crate base.
- 1. Slide shipping crate base clear.
- 2. Lower magnet to 50mm(2") above floor.
- 3. Move magnet to desired final location and place on 12mm (0.5") plywood sheet and wooden 100mm x 100mm (4" x 4") blocks (refer to figure 2).
- 4. Install 45° Mounting Brackets using M16 x 30 Hex bolts, flat and spring washers (refer to figure 2).
- 5. Lift magnet from top lifting eye about 50mm (2") remove 100mm x 100mm (4") wooden block located next to 45° mounting bracket (refer to figure 2).
- 6. Lower magnet so that it rests only on the front 100mm x 100mm (4") wooden block (refer to figure 3).
- 7. Install shackles and lifting sling to BOTH FRONT EYEBOLTS. Caution, keep hands and feet clear of magnet and 45° brackets during the following operation. Take weight of magnet and push the top front of the magnet rearward. The magnet weight should move over center. Lower magnet so that it rests on the 45° mounts (refer to figure 3 and 4).

Rolling or Rolling/Rotating Base Mounting (refer to Drawing 11900480)

Caution do not attempt to move magnet and rolling base or rolling/rotating base until the magnet has been firmly bolted down to the base (refer to figure 6).

- 1. To mount on rolling base or rolling/rotating base lift magnet from BOTH FRONT EYEBOLTS high enough to clear top of base (refer to figure 5).
- 2. Slide rolling base or rolling/rotating base underneath, lower magnet to 12mm (0.5") above base top surface (refer to figure 5).
- 3. Position rolling base or rolling/rotating base so the tapped holes in the base are aligned with the 45° mounting bracket hole (refer to figure 5).
- 4. Lower magnet onto rolling base or rolling/rotating base assembly (refer to figure 5).
- 5. Secure magnet and 45° mounting assembly to rolling base or rolling/rotating base with M16 x 25 long Hex Head Bolts (refer to figure 6).
- 6. Move magnet and rolling base or rolling/rotating base to desired location.
- 7. Screw down the four support legs located on each corner of the rolling or rolling/rotating base until the wheels clear the floor by 6mm (.25").
- 8. Secure the support legs with the locknut.
- 9. Secure rolling/rotating base to an adequate concrete floor to prevent movement and possible injury to personnel during an earthquake.

INSTALLATION

Pole Cap Selection and Installation (Refer to Drawing 11801602/11801603)

Using the field uniformity and induction curves determine the most desirable pole cap; cylindrical or tapered. In general:

If a uniform field is required use a cylindrical cap.

If a high field is required use a tapered cap.

The pole caps are machined from low carbon steel. This material is relatively soft and easily damaged. Since the pole caps are heavy and awkward to manipulate it is advisable to cover the pole faces to protect them from damage.

Pole cap removal using lifting eye bolt. (Refer to Drawing 11801602/11801603)

- 1. Turn off the power supply
- 2. Draw pole caps about 20mm into the pole sleeves, so the tapped M10 holes on the pole cap are still clear.
- 3. Fit the pole cap lifting eye bolt firmly into the top tapped hole (M10) of the pole cap to be removed.
- 4. Draw in the pole cap that is not to be removed until it is flush with the pole sleeve.
- 5. Tape cardboard or something similar to the face of the pole cap that is not to be removed to protect it from damage.
- 6. Support the pole weight, using a sling and overhead crane (approx. weight 38kg/84lbs).
- 7. Remove the axial retaining stud nut (item 33 on drawing 11801602/11801603).
- 8. Place the pole cap retaining stud wrench (item 2 on drawing 18900010) onto the end of the retaining stud (item 6 on drawing 11801602/11801603).
- 9. Remove retaining stud (item 6 on drawing 11801602/11801603) while supporting the pole cap.
- 10. Carefully rock the pole cap to break the adhesion to the pole and remove from the magnet

If lifting equipment is not available, the pole cap can be removed using the pole cap removal tool, using the following procedure.

Pole cap removal using pole cap removal tool. (Refer to Drawing 11801602/11801603)

- 1. Turn off the power supply
- 2. Draw pole caps about 20mm into the pole sleeves, so the tapped M10 holes on the pole cap are still clear.
- 3. Fit the pole cap removal tools (item 11 on drawing 18900010) firmly into two opposite tapped holes (M10) on the pole cap to be removed.
- 4. Tape cardboard or something similar to the face of the other pole cap to protect it from damage.
- 5. Loosen the axial retaining stud nut 1 turn, but do not remove. (item 33 on drawing 11801602/11801603).
- 6. Use two people to support the weight of the pole cap (approx. weight 38kg/84lbs).
- 7. Place the pole cap retaining stud wrench (item 2 on drawing 18900010) onto the end of the retaining stud (item 6 on drawing 11801602/11801603).
- 8. Remove retaining stud (item 6 on drawing 11801602/11801603) while supporting the pole cap.
- 9. *Carefully* rock the pole cap to break the adhesion to the pole and remove from the magnet

INSTALLATION

Pole cap fitting.

- 1. Ensure the pole caps, pole cores, and pole sleeves are clean and free from debris.
- 2. Reverse the above pole cap removal sequence.

Electrical Circuit

Never connect or remove cables from the magnet with the power supply connected. The stored energy in the magnet can cause arcing resulting in severe injury or equipment damage.

The magnet has two coils which may be connected in series (140A/76V) Model: 3474-140 or in series/parallel (280A/38V) Model: 3474-280 to match different power supplies. Refer to drawing 11801602/11801603. The power supply cables should be connected directly to the DC current terminals marked + and -. Recommended current cable is stranded copper of 120mm² cross section (250MCM) for the 280A/38V coil connections. For 140A/76V coil connections use 70mm² cross section (2/0 AWG) standard copper current cables. Refer to drawing 13900030 for details.

Because the magnet stores a significant amount of energy in its magnetic field, special care should be taken to insure that the current terminations are secure and cannot work loose in operation. Local heating at the terminations can cause rapid oxidation leading to a high contact resistance and high power dissipation at the terminals. If left unattended this can cause enough local heating to damage the terminals and the coils.

Interlocks

Six thermal sensors Elmwood 3450G Part Number 3450G611-1 L50C 89/16 are wired in series and terminated in positions 3 and 4 on the Interlock Terminal block. They are normally closed, opening when the coil central cooling plate temperature exceeds $50^{\circ}C + /3^{\circ}C$. The flow switch is connected to terminals 1 and 2. The contacts are normally open, closing when the water flow exceeds approx. 10 l/min.

INSTALLATION

Cooling

The Model 3474 can be operated to an average coil temperature of 70° C. Assuming an ambient laboratory temperature of 20° C and a temperature coefficient of resistivity of 0.00393, the hot resistance of the coil should not exceed 20% more than the ambient temperature "cold" resistance. The coil thermal sensor will open when the coil cooling plate temperature exceeds approximately 50° C. Clean, cool (12° C - 20° C) water at 15 l/min and 2.0 bar (30 psid) should be used to cool the magnet. The cooling tubes are not electrically connected to the coils so no electrochemical corrosion will occur. If the water supply contains particulates, a 50 micron filter should be placed before the input to the magnet to avoid unreliable operation of the flow switch.

For continuous operation of the magnet it may be appropriate to use a recirculating chiller to reduce water and drainage costs. The chiller capacity will depend on whether cooling is required for the magnet alone or magnet and power supply. For the Model 3474 Electromagnet alone a suitable chiller is the Neslab HX-300 with PD-2 pump. Use distilled or deionized water with a biocide to prevent bacterial growth and corrosion. Do not use corrosion inhibitors in high quality electrical systems since the water conductivity is increased which can result in increased leakage currents and electrochemical corrosion.

At currents of below 40A for coils that are series connected or 80A for series/parallel connected coils the Model 3474 can be operated safely without water cooling. However the coil temperature will vary with the power dissipation. This results in dimensional and permeability changes of the magnet yoke. Air cooling is not suitable when high field stability is required.

Freon, oil, ethylene glycol or other cooling mediums can be used. The flow required will be approximately inversely proportional to their specific heats. An experimental determination of the flow and pressure required will be necessary.

Avoid cooling the magnet below the dew point of the ambient air. Condensation may cause electrical shorts and corrosion.

During operation the resistance can be checked using a voltmeter across each coil. The voltage will rise to a constant value once thermal equilibrium has been reached. If it is desired to save water, the flow can be reduced until the hot resistance is approached. NOTE: This adjustment must be made slowly enough to allow for the thermal inertia of the coils.

OPERATION

General

The magnet operates as a conventional electromagnet.

1. Adjust the poles to the desired gap with the poles approximately symmetrical about the center magnet line. To reduce mechanical backlash when the magnetic field is applied, it is best to set the poles by increasing the gap.

2. Adjust the cooling water flow to about 15 liters/min (4 US gpm). For operation at less than maximum power the water flow may be correspondingly reduced.

3. Turn on the power supply and increase the current until the desired field is reached.

Calibration

The induction curves may be used to estimate the field in the air gap to within four or five percent. More accurate field determination may be obtained by deriving experimentally a calibration curve for the particular pole and air gap combination being used. Magnetic hysteresis in the yoke and poles can cause an error of 30 to 70G (3 to 7mT) with an arbitrary application of such a calibration curve. This effect may be reduced to less than one percent by following a prescribed 'current setting schedule' designed to make the magnet 'forget' its prior magnetic history. The schedule should of course be used both in establishing the calibration curve and in its subsequent use. A possible schedule would be:

From zero current, increase to maximum current and reduce again to zero current. Increase again to maximum current and reduce to the current to give the desired field setting. Approaching the desired field from a higher setting will typically produce better field uniformity. This is because the field changes at the pole edges will normally lag the field change at the center thereby helping to compensate the radial decrease in field.

Greater precision in setting up the calibration curve will be achieved with the use of a digital gaussmeter and by making a numerical table. This table used with an interpolation routine will eliminate the error associated with reading a graph.

In any event, three points need to be remembered:

1. A calibration curve or table is only as good as the precision employed in generating it.

2. The field is defined only at the point it is measured. It will generally be different at a different point in the air gap. For example, the induction curves refer to the field on the pole axis and at the center of the air gap (median plane).

3. The field is most directly a function of the current in the magnet coils. Voltage across the coils is not a good measure of field since the electrical resistance of the coils depends on the temperature (about 0.4% per degree Celsius).

OPERATION

Field Control Operation

The necessity to use calibration curves can be avoided by using a field controller to sense the magnetic field and provide a corresponding power supply control signal through the power supply programming inputs. Contact GMW for suitable instrumentation.

MAINTENANCE

Periodically check that the pole adjustment mechanism is clean, properly lubricated and free of grit and dirt, which may cause binding of the mechanism. Be very careful not to damage the relatively soft pole surface since this may degrade the magnetic field uniformity in the gap.

Note that the surface treatments used provide good corrosion protection but in order to maintain the inherent mechanical precision of the magnet, heavy build-up of plating materials is deliberately avoided. As a result, high humidity or otherwise seriously corrosive atmospheres can cause corrosion. Periodically apply an appropriate corrosion protection, particularly when the magnet is stored for an extended period.

Check the cooling water circuit to ensure the water is clean and free of debris and bacterial growth. Ensure the in-line water filter is clean.

STANDARD OPTIONS









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REVISIONS AFEVISIONS DESCRIPTION DRAFT DATE APPROVED 07/07/97 G.DOUGLAS NOTE: 1, CHG ITEM 3 04/07/04 G.DOUGLAS	e PULLEY/BEARING VIEW, ADD NOTE 2 03/07/08 G.DOUGLAS		SHIM WASHER, 14 X 26 X 0.1MM THICK SETSCREW 8-32 x 1/4" UNC PIN, SPRING M4 X 18L, SP/S BEARING, THRUST 0.5" SHAFT, BERG BEARING RETAINING RING, BERG N1624 BEARING, NEEDLE ROLLER, SDP	SPACER, WORM WORM SHAFT -18 PULLEY, 18 TEETH [for 0.5" shaft] BERG WORM	WORM MOUNT DESCRIPTION DESCRIPTION NOTE DO NOT SCALE FROM DRAWING FROM DRAWING REMOM DRAWING MARSHORE and DRAWING MARSHORE AND DRAWING MARSHORE AND DRAWING MARSHORE PROPERTIES AND DRAWING MARSHORE PROPERTIES AND DRAWING AND DRAWING NO. Description NOTE DO NOT SCALE FROM DRAWING MARSHORE AND DRAWING MARSHORE PROPERTIES AND DRAWING MARSHORE PROPERTIES AND DRAWING NO. Description A00T MARSHORE MARSHORE PROPERTIES AND DRAWING MARSHORE PROPERTIES AND DRAWING NO. DESCRIPTION MARSHORE PROPERTIES AND DRAWING NO. DESCRIPTION MARSHORE AND DRAWING MARSHORE PROPERTIES AND DRAWING NO. MOTO AND DRAWING AND DRAWI	scale 1:1 Wr kg SHEET 1 OF 1
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CUSTOM OPTIONS

EXCITATION CURVES

GMW Associates Electromagnet Excitation Plot Field Vs Gap

Contract No: Customer:		Page: 1 of 1		Date: Engr:	Feb 04,2003 Y. Qin
Model: Serial No:	3474	Power Supply: Serial No:		Set Current: Target Field:	140 Amps
Pole Face: Serial No: Pole Gap: Pole Spacers:	As per table below None As per table below None	Position: Notes:	X=0, Y=0, Z=0		



GMW Associates Electromagnet Excitation Plot Field Vs Current








Contract No: Customer:		Page: 4 of 7	7	Date: Engr:	March 03, 86 R.Gummer
Model: Serial No:	3474 01	Power Supply: Serial No:		Set Current: Target Field:	
Pole Face: Serial No: Pole Gap: Pole Spacers:	100 mm None As per table below None	Position: Notes:	X=0, Y=0, Z=0		



Contract No: Customer:		Page: 5 of	7	Date: Engr:	Feb 4, 03 Y.Qin
Model: Serial No:	3474 48	Power Supply: Serial No:		Set Current: Target Field:	
Pole Face: Serial No: Pole Gap: Pole Spacers:	75 mm None As per table below None	Position: Notes:	X=0, Y=0, Z=0		











Section 9

TEST DATA









Engr: E. Schulze Date: 29 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 150 mm Pole Gap: 30 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X ٠ -20 -40 õ C7955 100 Amp. 3474-140 60 -80 Field (Tesla) 2:1600000 2:1400000 2.0600000 + 2.2400000 2.1800000 2.1200000 2.0800000 2.2200000 2.2000000 2.1000000 Contract No: Serial No Model Note:

Filename: SC7955 Uniformity Plot 2.507

Engr: E. Schulze Date: 29 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 150 mm Pole Gap: 30 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X -20 -40 õ C7955 140 Amp 3474-140 60 -80 Field (Tesla) 2.2000000 + 2.3800000 2.3200000 2.2600000 2.2400000 2.2200000 2.3600000 2.3400000 Contract No: Serial No Model Note:

Filename: SC7955 Uniformity Plot 2.507

Engr: E. Schulze Date: 29 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 8 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** 4 X Position (mm) Pole Face: 150 mm Pole Gap: 40 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X -20 4 Ģ C7955 100 Amp. 3474-140 60 -⁸⁰ Field (Tesla) 1.860000 1.860000 1.7800000 + 1.9400000 1.9200000 1.9000000 1.8800000 1.8400000 1.8200000 1.8000000 Contract No: Serial No Model Note:

Filename: SC7955 Uniformity Plot 3.507

Engr: E. Schulze Date: 29 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 150 mm Pole Gap: 40 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X -20 -40 õ C7955 140 Amp 3474-140 60 -80 Field (Tesla) 2.0800000 -2.0600000 -1.9600000 2.1800000 2.1400000 2.1200000 2.0400000 2.0200000 1.9800000 2.1600000 2.1000000 2.0000000 Contract No: Serial No Model Note:

Engr: E. Schulze Date: 29 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 6 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 150 mm Pole Gap: 50 mm Pole Spacers: Not fitted Fixed Axiz: Y=0, Z=0 Variable Axis: X -20 -40 õ C7955 100 Amp. 3474-140 60 -80 (sls9T) bl9iT 1.5800000 1.5600000 1.5600000 1.5000000 + 1.6400000 -1.6200000 1.6000000 1.5400000 1.5200000 Contract No: Serial No Model Note:

Engr: E. Schulze Date: 29 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** ٠ X Position (mm) Pole Gap: 50 mm Pole Spacers: Not fitted Fixed Axiz: Y=0, Z=0 Variable Axis: X Pole Face: 150 mm ٠ -20 -40 õ C7955 140 Amp 3474-140 60 -80 Field (Telsa) 1.7400000 + 1.9400000 1.9200000 1.9000000 1.8800000 1.8600000 1.8000000 1.7800000 1.7600000 1.8200000 Contract No: Serial No Model Note:

Filename: SC7955 Uniformity Plot 4.507

Engr: E. Schulze Date: 29 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 150 mm Pole Gap: 60 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X -20 -40 õ C7955 100 Amp. 3474-140 60 -80 Field (Tesla) 1.360000 1.3600000 1.2800000 + 1.4400000 -1.4200000 1.4000000 1.3800000 1.3400000 1.3200000 1.3000000 Contract No: Serial No Model Note:

Engr: E. Schulze Date: 29 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 150 mm Pole Gap: 60 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X -20 -40 õ C7955 140 Amp 3474-140 60 -80 **Field (Tesla)** 1.6600000 1.6400000 1.5600000 + 1.7400000 1.6800000 1.5800000 1.7200000 1.7000000 1.6200000 1.6000000 Contract No: Serial No Model Note:

Engr: Mike Duffy Date: 28 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 6 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 150 mm Pole Gap: 70 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X -20 -40 õ 3474-140 C7955 100A 60 -80 1.1200000 + Field (Tesla) 1.2000000 1.1800000 1.1800000 1.2600000 1.2400000 1.2200000 1.1400000 1.1600000 Contract No: Note: Serial No Model

Filename: SC7955 Uniformity Plot 6.507

Engr: Mike Duffy Date: 28 January, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 150 mm Pole Gap: 70 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X -20 -40 õ 3474-140 C7955 140A 60 -80 **Field (Tesla)** 1.5000000 1.4800000 1.4000000 + 1.5800000 1.5200000 1.4600000 1.4200000 1.5600000 1.5400000 1.4400000 Contract No: Serial No Model Note:

Engr: E. Schulze Date: 12 February, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 200 mm Pole Gap: 30 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X -20 -40 õ C7955 100 Amp. 3474-140 60 -80 Field (Tesla) 2.0120000 2.0100000 2.0020000 + 2.0200000 2.0140000 2.0080000 2.0040000 2.0180000 2.0160000 2.0060000 Contract No: Serial No Model Note:

Filename: SC7955 Uniformity Plot 12.507

Engr: E. Schulze Date: 12 February, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 80 6 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** X Position (mm) Pole Face: 200 mm Pole Gap: 30 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X -20 -40 õ C7955 140 Amp 3474-140 60 -80 Field (Tesla) 2.1350000 -2.1200000 + 2.1500000 2.1450000 2.1400000 2.1300000 2.1250000 Contract No: Note: Serial No Model

Filename: SC7955 Uniformity Plot 12.507

	LABORATORY EL	GMW ASSOCI ECTROMAGNET UNIFO	ሏTES DRMITΥ PLOT - Field	Vs Position
Model Serial No Contract No: Note:	3474-140 09 C7955 100 Amp.	Pole Face: 200 mm Pole Gap: 70 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X	Pole SN:	Engr: E. Schulze Date: 12 February, 1997
1.2200000 1.2150000 1.2100000 1.200000 1.200000 1.200000 1.200000 1.2000000 1.2000000 1.2000000		Eleid vs Positi		
1.1900000		-20 0 X Position (mm)	20 40	60 80

	GMW ASSOCIATES LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position
Model Serial No Contract No: Note:	3474-140Pole Face: 200 mmPole SN:Engr. E. Schulz09Pole Gap: 70 mmPole Gap: 70 mm07955Pole Spacers: Not fittedPole Spacers: Not fitted140 AmpFixed Axis: Y=0, Z=0Variable Axis: X
Field (Tesla) 1.4650000 1.4650000 1.4650000 1.45500000 1.45500000 1.45500000 1.45500000 1.45500000 1.455000000 1.455000000 1.45500000 1.45500000 1.45500000 1.45500000 1.455000000 1.455000000 1.4550000000 1.45500000000000000000000000000000000000	Liefd vs Doition
1.4400000	B0 -60 -40 -20 40 60 80 -40 50 -80 -50 50 -50 50 -50 50 50 -50 50 50 50 50 50 50 50 50 50 50 50 50 5

Engr: E. Schulze Date: 12 February, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 8 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** Pole Face: 200 mm Pole Gap: 100 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X X Position (mm) 0 -20 -40 õ C7955 100 Amp. 3474-140 60 -80 Field (Tesla) 0.8700000 0.8650000 0.8900000 0.8450000 -0.8750000 0.8500000 0.8850000 0.8800000 0.8600000 0.8550000 Contract No: Serial No Model Note:

Filename: SC7955 Uniformity Plot 16.507

Engr: E. Schulze Date: 12 February, 1997 80 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - Field Vs Position 8 4 Pole SN: **GMW ASSOCIATES** 20 **Field vs Position** Pole Face: 200 mm Pole Gap: 100 mm Pole Spacers: Not fitted Fixed Axis: Y=0, Z=0 Variable Axis: X X Position (mm) 0 -20 -40 õ C7955 140 Amp 3474-140 60 -80 Field (T150000 1.1400000 1.0900000 1.1350000 1.1300000 1.1200000 1.1100000 1.1050000 1.1000000 1.0950000 1.1250000 Contract No: Serial No Model Note:

Engr: E. Schulze Date: 14 February, 1997 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - 10mm Cube Pole SN: **GMW ASSOCIATES Field vs Position** Position X, Y, Z (mm) Pole Face: 200 mm Pole Gap: 50 mm Pole Spacers: Fitted Fixed Axis: Variable Axis: X, Y, Z 100ppm 3474-140 09 C7955 1.0T **Field (Telsa)** 1.0022000 1.0022800 1.0022600 -1.0022400 1.0021400 1.0021200 1.0022200 1.0021600 Contract No: Serial No Model Note:

Engr: E. Schulze Date: 14 February, 1997 LABORATORY ELECTROMAGNET UNIFORMITY PLOT - 10mm Cube Pole SN: **GMW ASSOCIATES Field vs Position** Position X, Y, Z (mm) Pole Face: 200 mm Pole Gap: 50 mm Pole Spacers: Fitted Fixed Axis: Variable Axis: X, Y, Z 100ppm 3474-140 C7955 1.5T 60 Field (Tesla) 1.5001000 1.5000800 1.4999000 1.5000600 1.5000400 1.5000200 1.4999800 1.4999600 1.4999400 1.4999200 Contract No: Serial No Model Note:

Engr: E. Schulze Date: 14 February, 1997 T axis, x=-20 Z axis, x=-10 Z axis, x=10 Z axis, x=20 <u>→</u>Z axis, x=-5 ×−Z axis, x=0 <mark>★</mark> Z axis, x=5 -50ppm -+50ppm - +25ppm LABORATORY ELECTROMAGNET UNIFORMITY Z-Axis as a function of X-Axis 25 20 Ρ 15 9 Pole SN: **GMW ASSOCIATES** X or Z Position (mm) ŝ 9 Pole Spacers: Fitted Fixed Axis: Y=0 Variable Axis: X, Z Pole Face: 200 mm Pole Gap: 50 mm 0 မှ -10 ₽́q 50ppm -15 100nnm 3474-140 C7955 100A 60 -20 1.53950000 1.53985000 1.53980000 1.53975000 1.53970000 1.53960000 1.53955000 1.53990000 1.53965000 Contract No: Note: Serial No: Model: -25

GMW ASSOCIATES LABORATORY ELECTROMAGNET STABILITY PLOT





GMW ASSOCIATES LABORATORY ELECTROMAGNET STABILITY PLOT





17:11

17:39

18:08

18:37

19:06

Field

1.0021700

1.0021600

1.0021500

1.0021400

15:44

16:13

16:42

Section 10

DRAWINGS

Typical Applications:

Power Supplies

- Communication Equipment
- **Medical Equiopment**

Computers (Where High AMP Loads are Present)



The Series 3450/3455R is a snap-acting, nonadjustable precision thermostat especially suited for industrial and electrical equipment.

The 3450 (.390" or 10mm overall) is ideal for applications that require precision control of high electric loads to 8 Amp resistive.

The 3450R and 3455R have a patented metal insert rivet construction.

The 3455R (.484" or 12.5mm) overall, has higher spacing as required by European approval agencies. Model 3455RBV is an epoxy overmold version of the 3455R, specifically designed for electrical insulation or protection in a high humidity environment. Consult factory for performance qualifications.

To insure that a safe combination of thermostat and application is achieved, the purchaser must determine product suitability for their individual requirements.



*Series 3450/3450R/3455R/3455RBV

MODEL	BLECTRIC LIFE CYCLES	120 VAC	240 VAC	277VAC
3450	100,000	8.0A	-	-
3450R/	100,000	15A	8.3A	7.2A
3455R	100,000	4.4FLA 26.4LRA	22FLA 13.2LFA	-
	6,000	58RA348LRA	29FLA 17.4LRA	+
3455RBV	100.000	15A	8.3A	-
	6,000	5.8A 34.8LRA	2.9A 17.4LRA	

A: Amps FLA: Full Load Amps LRA: Locked Rotor Amps

Contacts are available for millivolt and milliamp applications. *Includes UL and CSA ratings.

Consult Elmwood Sensors for additional ratings.

Key Features:

- · Electric Rating to 15 Amp 120 VAC Resistive
- Environmental Exposure 0° to 350° F (-18° to 177° C)
- UL recognized and CSA certified and European Approved
- · Single-Pole, Single-Throw (SPST)
- · Pre-set and Tamperproof
- Variety of Mounting Brackets and Terminals Available

SERIES 3450/3450R/3455R/3455RBV 15 AMP THERMOSTATS

Standard Temperature Characteristics

Operating Temperature Range The tightest specification deter- mines the group		Toler Allow ± at temp set p	rance vable" mean erature oints		Stand Mean Differ Nomin betwe and ck points	and antial al degrees en opening ssing	Price Group*
	0 ±°F	pen ±°C	Ci ±°F	ose ±°C	°F	°C	
32° to 79°F 0° to 25°C	5 5 5 5	2.8 2.8 2.8 2.8	8 7 6	4.4 3.9 3.3 3.3	30-50 25-29 20-24 15-19	16-28 14-16 11-13 8-11	
80° to 200°F 25° to 95°C	5 5 5 6	2.8 2.8 2.8 2.2	8 7 6 5	4.4 3.9 3.3 2.8	30-50 25-29 20-24 15-19	16-28 14-16 11-14 8-11	1 11 11 11 11
201 to 250°F 96° to 120°C	6 6 6	4.4 3.9 3.3 2.8	8 7 6	4.4 3.9 3.3 2.8	30-50 25-29 20-24 15-19	16-28 14-16 11-14 8-11	
251 to 302°F 121.7° to 148.9°C	7 7 7 6	3.9 3.9 3.9 3.3	8 7 7 7	4.4 3.9 3.9 3.9	30-50 30-50 20-29 15-19	16-28 16-28 11-16 8-11	1 11 111 111

*Grouped according to level of accuracy required. Group I with greatest latitude is less expensive than Group II, etc. Please consult factory for temperature ranges, tolerances and differentials not noted. The operating

Prease consult incory for temperature ranges, tolerances and dimerentiats not noted. The operating temperature ranges include tolerances. The 2 tolerance shown have been established after careful review of many thermostat applications. Attempts should be made to establish the widest acceptable tolerance possible. For example, the chart may list a tolerance of $\pm5^{\circ}$ F ($\pm2.8^{\circ}$ C); however, $\pm5^{\circ}$ F ($\pm3.3^{\circ}$ C) may be acceptable for the application at reduced cost. Note: Temperature checking methods may be slightly different, and allowance for a 1.8° F (1° C) variance should be made to establish the widest acceptable to the application at reduced cost.

be considered.

See Section B of the Terminal and Bracket Guide for dimensional characteristics.

Operating Parameters

Dielectric Strength	MII-STD-202 Method 301 -2000 VAC 60 Hz -
	Terminal to Case
Insulation Resistance	Mil-STD-202 Method 302 Cond. B - 500 Megohms
	500 Volts DC applied
Environmental Exposure	0° to 350°F (-18° to 177°C)
Operating Temp. Range	32° to 302°F (0° to 150°C)
Contact Resistance	Mil-STD-202, Method 307 - 50 Millohms
Marking	MII-STD-1285
Weight	6 Grams (Brackets and wire leads not included)
Materials	Base: Phelonic
	Terminals: Plated Brass or Steel
	Closure: Aluminum, Stainless Steel, or Brass
	Brackets: Aluminum, Stainless Steel, or Brass
	Contacts: Silver

UL and CSA Listings

UL and CSA Listings are for use in equipment where the acceptability of the combination of the thermostar and equipment is determined by Underwriters' Laboratories, Inc. and/or the Canadian Standards Association.

UL File E36103, UI, File SA4469 (3455RBV only), UL File MH8267 (3455R only), CSA File 21048.

27 F61 SFRIES PENN FLOW SWITCHES

F61 SERIES FLOW SWITCH

STANDARD FLOW RATE - SPDT

The F61 flow switch is designed for use on liquid lines using water, ethylene glycol solutions, or other liquids not injurious to the brass and phosphor bronze parts that come in contact with the liquid. The SPDT contacts make or break an electrical circuit when flow starts or stops.

F61KB-11: NEMA 1 type enclosure.

F61MB-1: This flow switch meets NEMA type 4 requirements and is UL listed as raintight. Use on indoor or outdoor applications in high humidity atmospheres, on liquid lines handling fluids below dewpoint or below 32°F (0°C).

Use on lines carrying well water, swimming pool water, sea water, brine or ethylene glycol. Not for use with hazardous fluids or in hazardous atmospheres.

The bronze paddle is of three segments for use in pipes from 1 in. to 3 in diameter. Paddle segments may be removed or trimmed as needed. Catalog No. F61KB-11 and F61MB-1 include a 6 in. paddle for pipes 4 in. to 6 in.

Pipe Connection: 1 in. NPT.

TO ORDER: Specify F61KB-11 for NEMA 1 enclosure, F61MB-1 for NEMA 4 enclosure. ELECTRICAL RATINGS 120 208 240 277 Motor Ratings VAC 1 Horsepower 1 AC Full Load amp 16.0 88 8.0 52.8 48.0 AC Locked Rotor amp 96.0 Non-Inductive or 16 16 16 16 Resistance Load amp

Max Liquid Pressure: 150 PSIG (1034 kPa).

Min Liquid Temperature, F61KB-11: 32°F (0°C)

F61KB-11: 8% in. H (3 in. paddle), 4 in. W,

F61MB-1: 811/16 in. H (3 in. paddle), 451/64 in. W,

Max Liquid Temperature: 250°F (121°C).

F61MB-1: -20°F (-29°C).

Dimensions:

213/16 in. D.

213/16 in. D.

Pilot Duty - 125 VA, 24/277 VAC



ACTION ON INCREASE



F61KB-11 Replaces McDonneil & Miller FS4-3



F61MB-1 Replaces McDonnell & Miller FS8V-12

TYPICAL FLOW RATES - GPM (m³/hr) REQUIRED TO ACTUATE SWITCH

Line Pi	pe Size in.	. 1	11/4	11/2	2	21/2	. 3 -	4*	5*	6*	8*
Min	Flow Increase R to Y Closes	4.2 (1.0)	5.8 (1.3)	7.5 (1.7)	13.7 (3.1)	18.0 (4.1)	27.5 (6.2)	65.0 (14.8) 37.0† (8.4)	125.0 (28.4) 57.0† (12.9)	190.0 (43.1) 74.0† (16.8)	375.0 (85.2) 205.0† (46.6)
Adj 14	Flow Decrease R to B Closes	2.5 (0.6)	3.7 (0.8)	5.0 (1.1)	9.5 (2.2)	12.5 (2.8)	19.0 (4.3)	50.0 (11.4) 27.0† (6.1)	101.0 (22.9) 41.0† (9.3)	158.0 (35.9) 54.0† (12.3)	320.0 (72.7) 170.0† (38.6)
Max	Flow Increase R to Y Closes	8.8 (2.0)	13.3 (3.0)	19.2 (4.4)	29.0 (6.6)	34.5 (7.8)	53.0 (12.0)	128.0 (29.1) 81.0† (13.4)	245.0 (55.6) 118.0† (26.8)	375.0 (85.2) 144.0† (32.7)	760.0 (172.6) 415.0† (94.2)
Adj	Flow Decrease R to B Closes	8.5 (1.9)	12.5 (2.8)	18.0 (4.1)	27.0 (6.1)	32.0 (7.3)	50.0 (11.4)	122.0 (27.7) 76.0† (17.3)	235.0 (53.4) 111.0† (25.2)	360.0 (81.8) 135.0† (30.7)	730.0 (165.8) 400.0† (90.8)

 Flow rates for these sizes are calculated † These GPM figures are for switch with 6 in. paddle. For 4 in. and 5 in. line pipe the paddle is trimmed.

LOW FLOW RATE - SPDT

For use on liquid lines using water, ethylene glycol solutions, or other liquids not injurious to the brass and phosphor bronze parts. SPDT contact switch is activated by a low flow rate; however, it has a large flow capacity with minimum pressure drop. Typical applications include:

- Water purification and treatment systems.
- Booster pumps.
- Fast shut down on high input boilers to guard against circulation failure. Cooling systems for electronic tubes, bearings
- and compressors.

F61KD: NEMA 1 type enclosure.

F61MD: NEMA 4 (vaportight) enclosure.

ſ		Inlet and Outlet	Enclosure	Adjustment Rang	e — GPM (m³/hr)	Maximum	Maximum	Ship
	Catalog Number	Size Female NPT	NЕМА Туре	R to Y Closes Flow Increase	R to Y Opens Flow Decrease	Temp °F (°C)	Pressure PSIG (kPa)	wt Ib
t	F61KD-3	½ in. × ½ in.	1				450	
ľ	F61KD-4	³ /4 in. × ³ /4 in.	1	Minimum .6 (0.14)	Minimum .3 (0.07) Maximum 0.9 (0.2)	(121)	(1034)	2.2
	F61MD-2	3¼ in. × 3¼ in.	4			() =)		

* Non-Stock Item. Built to Order.

Dimensions: 51/32 in. H, 4 in. W, 213/16 in. D. TO ORDER: Specify Catalog Number only ELECTRICAL RATINGS

Min Liquid Temperature, F61KD: 32°F (0°C)

F61MD: -20°F (-29°C).

Motor Ratings VAC	120	208	240	277
Horsepower	1	1	1	
AC Full Load amp	16.0	8.8	8.0	
AC Locked Rotor amp	96.0	52.8	48.0	-
Non-Inductive or Resistance Load amp	16	16	16	16
Pilot Duty	125 VA, 2	4/277 V/	AC	



F61KD
















































